

V kapitole o porobovani poctu pone zptili, z dlouhoperiodicki, a schledni, mezi orbitami slenti v prui ruku malho parentu a lse raket zdmuon plu fony porobovho potencialu R plio studiu koduon

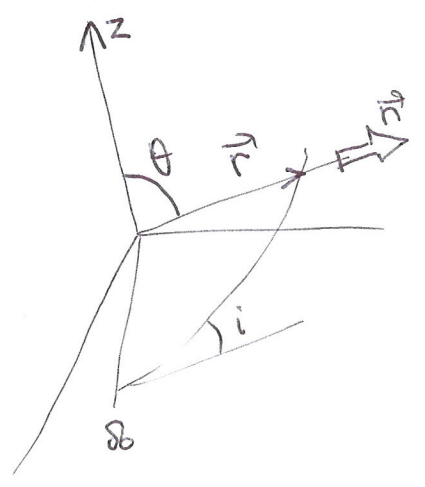
$$\bar{R} = \frac{1}{2\pi} \int_{-\pi}^{\pi} dl R(l)$$

teknickim vypocti R po prui dva zonalni ctely zopotencialu n=2 a 3:

$$R_{zon} = \frac{\mu}{r} \sum_{n \geq 2} \left(\frac{R}{r}\right)^n J_n P_n(\cos\theta) ; \mu = GM$$

$$R_2 = \frac{\mu}{2r} \left(\frac{R}{r}\right)^2 J_2 (3\cos^2\theta - 1)$$

$$R_3 = \frac{\mu}{2r} \left(\frac{R}{r}\right)^3 J_3 \cos\theta (5\cos^2\theta - 1)$$



$$\cos\theta = n_z = \cos f e_{pz} + \sin f e_{oz}$$

Pr vypocti R puzdeme od integraci prumeru l -> f: $r^2 df = a^2 \eta dl \rightarrow dl = df \frac{1}{\eta} \left(\frac{r}{a}\right)^2$

kvadrupoleni cast R2:

$$\bar{R}_2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} dl R_2 = \frac{\mu}{2a} \left(\frac{R}{a}\right)^2 J_2 \frac{1}{\eta} \frac{1}{2\pi} \int_{-\pi}^{\pi} df \left(\frac{r}{a}\right)^2 \left(\frac{a}{r}\right) \left(\frac{a}{r}\right)^2 (3\cos^2\theta - 1) =$$

$$= \frac{\mu}{2a} \left(\frac{R}{a}\right)^2 \frac{J_2}{\eta^3} \frac{1}{2\pi} \int_{-\pi}^{\pi} df (1 + \cos f) \left[3(\cos^2 f e_{pz}^2 + \sin^2 f e_{oz}^2 + 2\sin f \cos f e_{pz} e_{oz}) - 1 \right]$$

↳ da vedy po stredni phi

$$= \frac{\mu}{2a} \left(\frac{R}{a}\right)^2 \frac{J_2}{\eta^3} \left[\frac{3}{2} (e_{pz}^2 + e_{oz}^2) - 1 \right]$$

ozn. \vec{c} .. normovaný vektor k ose

(22)

pat $\underline{e_{p2}^2 + e_{Q2}^2 + c_2^2 = 1}$

melot jednotkový vektor \vec{e}
 projedovaj na ortogonálnu hradu
 $(\vec{e}_p, \vec{e}_Q, \vec{c})$

$$\boxed{\bar{R}_2 = \frac{\mu}{2a} \left(\frac{R}{a}\right)^2 \frac{J_2}{\eta^3} \left[\frac{3}{2} (1 - \frac{c_2^2}{\cos^2 i}) - 1 \right] = - \frac{\mu}{4a} \left(\frac{R}{a}\right)^2 \frac{J_2}{\eta^3} (2 - 3 \sin^2 i)}$$

$$= \frac{\mu}{4a} \left(\frac{R}{a}\right)^2 \frac{J_2}{\eta^3} (1 - 3 \cos^2 i)$$

oktupólu část R_3 :

$$\bar{R}_3 = \frac{1}{2\pi} \int_{-\pi}^{\pi} d\ell R_3 = \frac{\mu}{2a} \left(\frac{R}{a}\right)^3 \frac{J_3}{\eta} \frac{1}{2\pi} \int_{-\pi}^{\pi} df \left(\frac{r}{a}\right)^2 \left(\frac{a}{r}\right)^3 \left(\frac{a}{r}\right)^3 (5 \cos^3 \theta - 3 \cos \theta)$$

$$= \frac{\mu}{2a} \left(\frac{R}{a}\right)^3 \frac{J_3}{\eta^5} \frac{1}{2\pi} \int_{-\pi}^{\pi} df (1 + e \cos f)^2 \left[5 (\cos f e_{p2} + \sin f e_{Q2})^3 - 3 (\cos f e_{p2} + \sin f e_{Q2}) \right]$$

$$= \frac{\mu}{2a} \left(\frac{R}{a}\right)^3 \frac{J_3}{\eta^5} \frac{1}{2\pi} \int_{-\pi}^{\pi} df (1 + e \cos f)^2 \left[5 \cos^3 f e_{p2}^3 + 15 \cos^2 f \sin f e_{p2}^2 e_{Q2} + 15 \cos f \sin^2 f e_{p2} e_{Q2}^2 + 5 \sin^3 f e_{Q2}^3 - 3 \cos f e_{p2} - 3 \sin f e_{Q2} \right]$$

/ jkm
lidel
f → -f

$$= \frac{\mu}{2a} \left(\frac{R}{a}\right)^3 \frac{J_3}{\eta^5} \frac{1}{2\pi} \int_{-\pi}^{\pi} df (1 + 2e \cos f + e^2 \cos^2 f) \cdot (5 \cos^3 f e_{p2}^2 + 15 \cos f e_{p2} e_{Q2}^2 - 15 \cos^3 f e_{p2} e_{Q2}^2 - 3 \cos f e_{p2})$$

melot dvoje
zdvoje jen lide
mociny cos f

$$= \frac{\mu}{a} \left(\frac{R}{a}\right)^3 \frac{J_3 e}{\eta^5} \frac{1}{2\pi} \int_{-\pi}^{\pi} df (5 \cos^4 f e_{p2}^3 + 15 \cos^2 f e_{p2} e_{Q2}^2 - 15 \cos^4 f e_{p2} e_{Q2}^2 - 3 \cos^2 f e_{p2})$$

припоміне

$$\langle \cos^2 f \rangle = \frac{1}{2}$$

$$\langle \cos^4 f \rangle = \frac{3}{8}$$

(23)

$$= \frac{\mu}{a} \left(\frac{R}{a}\right)^3 \frac{J_3 e}{\eta^5} \left[\frac{15}{8} e_{pz}^2 + \frac{15}{2} e_{pz} e_{az}^2 - \frac{45}{8} e_{pz} e_{az}^2 - \frac{3}{2} e_{pz} \right] =$$

$$= \frac{3}{8} \frac{\mu}{a} \left(\frac{R}{a}\right)^2 \frac{J_3 e}{\eta^5} e_{pz} \left[5 e_{pz}^2 + 20 e_{az}^2 - 15 e_{az}^2 - 4 \right] =$$

$$= \frac{3}{8} \frac{\mu}{a} \left(\frac{R}{a}\right)^3 \frac{J_3 e}{\eta^5} e_{pz} \left[5 (e_{pz}^2 + e_{az}^2) - 4 \right]$$

$$1 - \cos^2 i = \sin^2 i$$
$$e_{pz} = \sin i \sin \omega$$

$$= \frac{3}{8} \frac{\mu}{a} \left(\frac{R}{a}\right)^3 J_3 \frac{e \sin \omega}{\eta^5} \sin i (5 \sin^2 i - 4)$$

$$= \frac{3}{8} \frac{\mu}{a} \left(\frac{R}{a}\right)^3 J_3 \frac{e \sin \omega}{\eta^5} \sin i (1 - 5 \cos^2 i)$$

$$(= \bar{R}_3)$$