Hydrodynamics of asteroid collisions and SPH method

- our problem
 SPH approximation
- 3. initial conditions4. two phases
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theoretical

Our problem is:

$$\begin{split} \frac{\mathrm{d}\rho}{\mathrm{d}t} &= -\rho\nabla\cdot\boldsymbol{v}\,,\\ \frac{\mathrm{d}\boldsymbol{v}}{\mathrm{d}t} &= -\frac{1}{\rho}\nabla P - \nabla\Phi + \frac{1}{\rho}\nabla\cdot\boldsymbol{S}\,,\\ \frac{\mathrm{d}U}{\mathrm{d}t} &= -P\nabla\cdot\boldsymbol{v} + \boldsymbol{S}\cdot\frac{1}{2}\left[\nabla\boldsymbol{v} + (\nabla\boldsymbol{v})^T\right]\,,\\ \nabla^2\Phi &= 4\pi G\rho\,,\\ \begin{pmatrix} A(\underline{\rho}-1) + B(\underline{\rho}-1)^2 + a\rho U + \frac{-b\rho U}{2} \end{pmatrix} \end{split}$$

$$P = \begin{cases} A\left(\frac{\rho}{\rho_{0}} - 1\right) + B\left(\frac{\rho}{\rho_{0}} - 1\right)^{2} + a\rho U + \frac{b\rho U}{\frac{U}{U_{0}}\frac{\rho^{2}}{\rho^{2}} + 1} & \text{pro } U < U_{\text{iv}}, \\ a\rho U + \left[\frac{b\rho U}{\frac{U}{U_{0}}\frac{\rho^{2}}{\rho^{2}} + 1} + A\left(\frac{\rho}{\rho_{0}} - 1\right) e^{-\beta\left(\frac{\rho_{0}}{\rho} - 1\right)} \right] e^{-\alpha\left(\frac{\rho_{0}}{\rho} - 1\right)} & \text{pro } U > U_{\text{cv}}, \end{cases}$$

$$\frac{\mathrm{d}\boldsymbol{S}}{\mathrm{d}t} = 2\mu_1 \, \frac{1}{2} \left[\nabla \boldsymbol{v} + (\nabla \boldsymbol{v})^T \right] + \left(\mu_2 - \frac{2}{3}\mu_1 \right) \nabla \cdot \boldsymbol{v} \, \boldsymbol{I} \,.$$

Aha!

Basic equations

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lagrangian formulation

$$\frac{\mathrm{d}\rho}{\mathrm{d}t} = -\rho \nabla \cdot \mathbf{v}, \qquad \qquad \text{eq. of continuity}$$

$$\frac{\mathrm{d}\boldsymbol{v}}{\mathrm{d}t} = -\frac{1}{\rho}\nabla P - \nabla\Phi + \frac{1}{\rho}\nabla\cdot\boldsymbol{S}\,, \qquad \qquad \text{Navier-Stokes}$$

$$\frac{\mathrm{d}U}{\mathrm{d}t} = -P\nabla \cdot \mathbf{v} + \mathbf{S} \cdot \frac{1}{2} \left[\nabla \mathbf{v} + (\nabla \mathbf{v})^T \right] \,, \qquad 1^{\mathrm{st}} \text{ law of thermodynamics}$$

$$\nabla^2 \Phi = 4\pi G \rho \,, \qquad \qquad \text{Poisson}$$

the P =
$$\begin{cases} A\left(\frac{\rho}{\rho_0} - 1\right) + B\left(\frac{\rho}{\rho_0} - 1\right)^2 + a\rho U + \frac{b\rho U}{\frac{U}{U_0}\frac{\rho_0^2}{\rho^2} + 1} & \text{pro } U < U_{\text{iv}}, \\ a\rho U + \left[\frac{b\rho U}{\frac{U}{U_0}\frac{\rho_0^2}{\rho^2} + 1} + A\left(\frac{\rho}{\rho_0} - 1\right) e^{-\beta\left(\frac{\rho_0}{\rho} - 1\right)} \right] e^{-\alpha\left(\frac{\rho_0}{\rho} - 1\right)} & \text{pro } U > U_{\text{cv}}, \end{cases}$$

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constitutive relation (for solids)

eq. of state (Tillotson 1962

Additional equations

• yielding criterion (von Mises 1913)

$$\boldsymbol{S} = f \boldsymbol{S}, \quad f = \min \left[\frac{Y^2}{3J_2}, 1 \right], \quad J_2 = S^{\alpha\beta} S^{\alpha\beta},$$

• flaws distribution (Weibull 1938) \rightarrow cracks, damage D

$$\sigma_{\alpha\beta} = \begin{cases} -P\delta_{\alpha\beta} + (1-D)S_{\alpha\beta} & \text{pro } P \ge 0, \\ -(1-D)P\delta_{\alpha\beta} + (1-D)S_{\alpha\beta} & \text{pro } P < 0. \end{cases}$$

$$\frac{\mathrm{d}D^{\frac{1}{3}}}{\mathrm{d}t} = \left[\left(\frac{c_g}{R_s}\right)^3 + \left(\frac{m+3}{3}\alpha^{\frac{1}{3}}\epsilon^{\frac{m}{3}}\right)^3 \right]^{\frac{1}{3}},$$

Grady & Kipp (1980)

smoothed particle \rightarrow SPH approximation

 continuum → a finite set of extended particles ("vehicles"), cf. Cossins (2010), Price (2012)



SPH formulation

• an integral representation of functions & discretisation

$$\boldsymbol{v}(\boldsymbol{r}) = \int_{\Omega} \boldsymbol{v}(\boldsymbol{r}') \delta(|\boldsymbol{r} - \boldsymbol{r}'|, h) \mathrm{d}\Omega \doteq \int_{\Omega} \boldsymbol{v}(\boldsymbol{r}') W(|\boldsymbol{r} - \boldsymbol{r}'|, h) \mathrm{d}\Omega,$$

$$\nabla \cdot \boldsymbol{v}(\boldsymbol{r}) = \int_{\Omega} [\nabla_{\boldsymbol{r}'} \cdot \boldsymbol{v}(\boldsymbol{r}')] W(|\boldsymbol{r} - \boldsymbol{r}'|, h) d\Omega =$$

$$= \int_{\Omega} \nabla_{\boldsymbol{r}'} \cdot [\boldsymbol{v}(\boldsymbol{r}') W(|\boldsymbol{r} - \boldsymbol{r}'|, h)] d\Omega - \int_{\Omega} \boldsymbol{v}(\boldsymbol{r}') \cdot \nabla_{\boldsymbol{r}'} W(|\boldsymbol{r} - \boldsymbol{r}'|, h) d\Omega =$$

$$= 0 \text{ na hranici}$$

$$= \int_{\partial\Omega} \boldsymbol{v}(\boldsymbol{r}') \widetilde{W(|\boldsymbol{r} - \boldsymbol{r}'|, h)} d\vec{\Gamma} - \ldots =$$

$$= -\int_{\Omega} \boldsymbol{v}(\boldsymbol{r}') \cdot \nabla_{\boldsymbol{r}'} W(|\boldsymbol{r} - \boldsymbol{r}'|, h) d\Omega = \int_{\Omega} \boldsymbol{v}(\boldsymbol{r}') \cdot \nabla_{\boldsymbol{r}} W(|\boldsymbol{r} - \boldsymbol{r}'|, h) d\Omega,$$

$$\nabla \cdot \mathbf{v}_i \doteq \sum_{j=1}^{N_{\text{okolo}}} \mathbf{v}_j \cdot \nabla W(|\mathbf{r}_i - \mathbf{r}_j|, h) \frac{m_j}{\rho_j},$$

SPH formulation (cont.)

- spatial derivatives → summations over nearest neighbours
- discretization in time (Euler or predictor/corrector)

$$\begin{split} \rho_i^{n+1} &= \rho_i^n - \Delta t \rho_i^n \sum_j \mathbf{v}_j^n \cdot \nabla W_{ij}(h) \frac{m_j}{\rho_j^n} \,, \\ \mathbf{v}_i^{n+1} &= \mathbf{v}_i^n - \frac{\Delta t}{\rho_i^n} \sum_j P_j^n \nabla W_{ij}(h) \frac{m_j}{\rho_j^n} + \frac{\Delta t}{\rho_i^n} \sum_j \mathbf{S}_j^n \cdot \nabla W_{ij}(h) \frac{m_j}{\rho_j^n} \,, \\ U_i^{n+1} &= U_i^n - \Delta t P_i^n \sum_j \mathbf{v}_j^n \cdot \nabla W_{ij}(h) \frac{m_j}{\rho_j^n} \,+ \\ &+ \sum_{\alpha=1}^3 \sum_{\beta=1}^3 S_{\alpha\beta}^n \frac{1}{2} \sum_j \left[v_{\beta j}^n \frac{\partial}{\partial x_\alpha} W_{ij}(h) + v_{\alpha j}^n \frac{\partial}{\partial x_\beta} W_{ij}(h) \frac{m_j}{\rho_j^n} \right] \end{split}$$

Smoothing Kernel

• suitable function: normal, compact, $\lim_{h \to 0} W(h) = \delta$, positive, decreasing, symmetric, smooth

$$W(R,h) = \frac{3}{2\pi h^3} \begin{cases} \frac{2}{3} - 4R^2 + 4R^3 & \text{pro } 0 \le R < \frac{1}{2} \\ \frac{4}{3} - 4R + 4R^2 - \frac{4}{3}R^3 & \text{pro } \frac{1}{2} \le R < 1 \\ 0 & \text{pro } R \ge 1 . \end{cases}$$



Obr. 2 — Kubický spline W(R, h) dle rovnice (15).

Initial & boundary conditions

- initial: $\mathbf{r} \sim 2$ spheres, diameters D_{target} , d_{project} , homogeneous, $\mathbf{v} = \text{const.}$, impact angle $\boldsymbol{\varphi}_{\text{imp}}$, no rotation
- no boundary (free surfaces)
- material parameters: ρ_0 , A, B, U_0 , a, b, α , β , U_{iv} , U_{cv} , μ , \underline{Y} , U_{melt} , k, $m \leftarrow a \ lot \ of...$
- numerical integration: adaptive timestep Δt , Courant number C = 1, timespan $t_2 \approx 3$ days

gravity free -> Fragmentation phase

don't worry, be happy...

• hydrodynamic approach, SPH5 code (Benz & Asphaug 1994)

 $D = 1 \text{ km}, d = 0.074 \text{ km}, v_{\text{imp}} = 5 \text{ km/s}, \varphi_{\text{imp}} = 45^{\circ}, Q/Q^{*}_{\text{D}} = 9.837$



gravity only -> Reaccumulation phase

 N-body approach, k-d tree, only spheres, perfect merging, pkdgrav code (Richardson et al. 2009)



i.e. *three*-dimensional → *k*-d tree

- split a group of points according to x, y, z, x, ... coordinates
- gravity approximation, nearest-neighbour search, ...
- 4th-order multipole expansion for particle⇔cell interactions
- opening angle $\varphi \simeq 0.5$, large vs small
- alternatives: linked-list (in SPH5)



Uncertainties related to SPH

- material parameters (moduli, flaws)
- state equation, phase transitions (e.g. ANEOS, SESAME)
- chemical reactions (!) in gaseous phase
- *total* damage → dust clouds?
- bouncing and friction in reaccumulation phase
- no information on fragment shapes and rotation yet
- laboratory experiments, e.g. for icy projectiles



Livermore ↓

Observed asteroid families ~ finally!

• e.g. Nesvorný et al. (2015), Brož et al. (2013), ...



Parent-body size(s)

- a simplified scaling (Durda et al. 2007), cf. Tanga et al. (1999)
- uncertainties: multiple fits have low χ^2 , interlopers
- systematics: number & distribution of SPH particles



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Monte-Carlo collisional models

(e.g. Boulder code, Morbidelli et al. 2009)

- Monte-Carlo approach
- number of disruptions
- parametric relations (SPH)
- largest remnant
- largest fragment
- SFD slope of fragments
- dynamical decay

pseudo-random-number generator for rare collisions within one time step

specific energy $Q = \frac{1}{2} m_j v^2 / M_{tot}$ Q_D^* ... scaling law focussing

$$n_{ij} = p_{i}(t)f_{g}\frac{(D_{i}+d_{j})^{2}}{4}n_{i}n_{j}\Delta t$$

$$M_{\rm LR} = \left[-\frac{1}{2} \left(\frac{Q}{Q_D^{\star}} - 1 \right) + \frac{1}{2} \right] M_{\rm tot} \quad \text{for } Q < Q_D^{\star}$$

$$M_{\rm LR} = \left[-0.35 \left(\frac{Q}{Q_D^{\star}} - 1 \right) + \frac{1}{2} \right] M_{\rm tot} \quad \text{for } Q > Q_D^{\star}$$

$$M_{\rm LF} = 8 \times 10^{-3} \left[\frac{Q}{Q_D^{\star}} \exp\left(- \left(\frac{Q}{4Q_D^{\star}} \right)^2 \right) \right] M_{\rm tot}$$

$$q = -10 + 7 \left(rac{Q}{Q_D^{\star}}
ight)^{0.4} \exp\left(-rac{Q}{7Q_D^{\star}}
ight)$$

Monte-Carlo collisional models

- for rubble-piles see Cibulková et al. (2014)
- for $D_{PB} = 1$ km see Ševeček et al. (in prep.)
- still some problems with energy conservation: initial decompression wave, double precision, increased artificial viscosity (to resolve shock-wave)



- 1:1 mean-motion resonance with Jupiter, Lagrange points
- resonant elements ← approximate integrals of motion



Brož & Rozehnal (2011), Rozehnal et al. (submitted)

- hierarchical clustering (Zappalà et al. 1995), "randombox"
- families: Eurybates, Hektor, 1996 RJ, Arkesilaos & Ennomos, 2001 UV₂₀₉



Figure 4. The statistical significance p expressed as colour on the logarithmic scale for observed asteroids in the proper semimajor axis vs proper inclination plane $(a_p, \sin I_p)$ (i.e. the same data as in Figure 1). L_4 Trojans are on the left, L_5 Trojans on the right. We computed the values of p for 7 times 18 boxes using our "randombox" method The range in proper eccentricity is 0.00 to 0.20. Statistically significant groups appear as orange boxes and they correspond to the families reported in Table 1.

Hektor family, an exceptional (primitive) D taxonomical



Figure 14. A comparison of SPH simulations of a disruption of a single body (basalt) with diameter $D_{\text{target}} = 250 \text{ km}$, by an impactor with the diameter $D_{\text{imp}} = 48 \text{ km}$ (silicate ice) (*left*) and a disruption of a bilobe basalt target, with $D_{\text{target}} = 198 \text{ km}$ for each sphere, by an impactor with $D_{\text{imp}} = 46 \text{ km}$ (silicate ice) (*right*). Time elapsed is t = 80.1 s in both cases. There are notable physical differences between the two simulations, especially in the propagation of the shock wave, which is reflected from free surfaces, the number of secondary impacts, or the fragmentation (damage) of the target. Nevertheless, the amount of ejected material and the resulting size-frequency distributions do not differ that much (cf. Figure 11).

- differences of SFD rather minor, thought
- parameter space of impact geometries much larger!





Figure 12. A simulation of evolution of the SFD of a synthetic Hektor family due to a ballistic transport and chaotic diffusion. One can see here a rapid change of SFD within the first 1 Myr after the breakup as the fragments of the impactor leaved the libration zone in our impact geometry. This ballistic transport resulted in a reduction of the number of particularly larger bodies in our case. Further evolution due to the chaotic diffusion seems to cause the reduction of mostly smaller bodies.

2:1 resonance with Jupiter

- unstable asteroids ← delivered by YE (Brož et al. 2005) easy...
- stable asteroids (Chrenko et al. 2015)

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• two stable islands A & B, $\tau \simeq 1$ Gyr, ratio 1:10



2:1 resonance with Jupiter

fifth planet & jumping-Jupiter scenario (Nesvorný & Morbidelli 2012)





Figure 7. Orbital evolution of giant planets in the fifth giant planet scenario, adopted from Nesvorný & Morbidelli (2012), during the jumping-Jupiter instability, as it was reproduced by our modified integrator. We plot the time *t* versus the semimajor axis *a*, the pericentre *q* and the apocentre *Q*. Each evolutionary track is labelled with the name of the corresponding giant planet.

simulation of the resonant capture from the outer main belt in the fifth giant planet scenario (Nesvorný & Morbidelli 2012). We plot the e les in the resonant semimajor axis a_r versus resonant eccentricity e_r plane. The vertical line indicates an approximate location of the 2:1 re n migrates inwards together with Jupiter. The integration time is shown in three of the panels (t = 0, 2, 6.26 and 10 Myr) and corresp in Fig. 7. The dashed arrows and lines indicate an approximate extent of the libration zone in the case of the migrating and stable resonant provide to bottom and left to right, the plots show: the initial conditions, the relaxed population of test particles prior to jump, the stat -Jupiter instability and the final state. Note that all test particles are depicted in terms of resonant elements for simplicity (even the non-

2:1 resonance with Jupiter

- problem: steep SFD $\gamma = -4.5$, usually due to recent collision
- *but* no observable family
- solution: a significant change of SFD due to spatial gradient



Figure 16. Dependence of the absolute magnitude H on the proper semima-

Finite element method

• Ševeček et al. (2015), notation Langtangen (2003):

Individual Boulders on Itokawa



cf. Lowry et al. (2014)

- 3-dimensional heat diffusion (Golubov & Krugly 2012, Ševeček et al. 2015) → non-negligible YORP torques
- uncertainties: SFD of boulders, thermal parameters
- systematics: real shapes



Other remaning problems:

- 3D heat diffusion in small irregular meteoroids
- planetesimals embedded in protoplanetary disks versus mean-motion resonances (Chrenko & Brož, in prep.)

